Open book and notes.

Four Problems, Three Pages

Part I. A <u>causal LTI system</u> is defined by the z-transform

$$H(z) = \frac{10z^{-1}}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 + \frac{1}{2}z^{-1}\right)}.$$

- (a) Specify the region of convergence (ROC) for H(z).
- (b) What are the two poles and the two zeros of H(z)?
- (c) Is the system stable?

**Part II.** A real discrete-time signal x[n] is defined

$$x[n] = \left(\frac{1}{4}\right)^n u[n] + 2u[n-2]$$

Determine X(z) and its region of convergence.

## Part III.

(a) Determine a simple discrete-time <u>difference equation</u> that has a system function described by the following pole-zero diagram.



zeros:  $-0.1 \pm j1.1$ ; and 0 poles:  $0.4 \pm j0.4$ , and 0.5

(b) Sketch a block diagram for a *Direct Form II* filter structure that will implement the difference equation.

**Part IV**. A peculiar upsampling system called the "Reham Processor" takes an input sequence and inserts a zero sample between *pairs* of its input samples. In other words, for an input sequence x[n] the output sequence y[n] is

x[0], x[1], 0, x[2], x[3], 0, x[4], x[5], 0, x[6], x[7], 0, ...

Note that no samples are lost in the Reham Processor: we can obtain the original sequence again from y[n].

We can model this system as shown below.



 $\rightarrow$  Recall that for a downsampling factor *M*, the spectral effect is:

$$X_{d}\left(e^{j\omega}\right) = \frac{1}{M} \sum_{i=0}^{M-1} X\left(e^{j\left(\omega/M - 2\pi i/M\right)}\right)$$

 $\rightarrow$  Recall that for an upsampling factor *L*, the spectral effect is:  $X_u(e^{j\omega}) = X(e^{j\omega L})$ 

Using the formulae for the effects of a delay by  $z^{-1}$ , downsampling and upsampling on the signal spectrum, write mathematical expressions *in terms of* the input spectrum  $X(e^{j\omega})$  for

 $X_l(e^{j\omega}),$ 

 $X_{dl}(e^{j\omega}),$ 

 $X_{ul}(e^{j\omega}),$ 

and  $X_{u2}(e^{j\omega})$